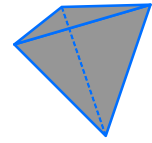


Simplicial complexes [scx]



① Building block: a geometric simplex [gsx] in \mathbb{R}^d

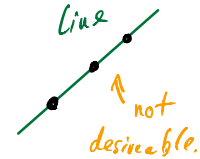
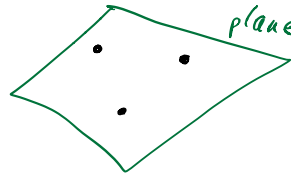
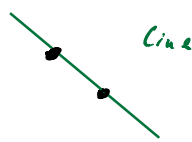
$$U = \{v_0, v_1, \dots, v_k\} \subset \mathbb{R}^d$$

Def: an affine combination of U is any expression (point) of the following:

$$\sum_{i=0}^k \alpha_i \cdot v_i, \quad \sum_{i=0}^k \alpha_i = 1.$$

(if $\alpha_i \geq 0, \forall i \rightarrow$ convex combination).

Example



Def: U are affinely independent if no v_i is an affine combination of other points in U .

Prop: U are aff. independent $\Leftrightarrow \{v_1 - v_0, v_2 - v_0, \dots, v_k - v_0\}$ is lin. indep.

Example:

- 2 pts are aff. indep iff they are different
- 3 - - - - - iff they are not colinear
- 4 - - - - - iff they do not lie on the same plane

Def: A geometric simplex [sx] $\sigma = \sigma^k$ in \mathbb{R}^d is $\text{conv}(U)$ of an affinely independent set U .



$\rightarrow U$... vertices of σ

$\rightarrow \dim(\sigma) = k$

\rightarrow edges of σ : convex combos of pairs from U .

$\rightarrow \sigma$ is spanned by U , or $\sigma = \langle v_0, v_1, \dots, v_k \rangle$

\rightarrow if τ is a sx spanned by a subset of U , we say:

- τ is a face of σ $\tau \subseteq \sigma$
- σ is a coface of τ
- τ is a facet of σ if $\dim(\tau) = \dim(\sigma) - 1$.

→ $\sigma \cong D^k$

→ Each $x \in \sigma$ can be expressed uniquely as

$$x = \sum_{i=0}^k \alpha_i v_i \quad \text{barycentric coordinates of } x.$$

② Geometric simplicial complexes [gscx, scx]

Def: A gscx K in \mathbb{R}^d is a (finite) collection of geometric simplices, so that:

① $\sigma \in K, \tau \leq \sigma \Rightarrow \tau \in K$

② $\sigma, \tau \in K \Rightarrow \sigma \cap \tau$ is a face of σ and τ (or empty).

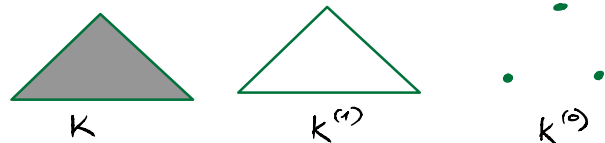
↳ dim(K) = $\max_{\sigma \in K} \dim(\sigma)$

↳ vertices(K) = $\bigcup_{\sigma \in K} \text{vertices}(\sigma)$

↳ edges(K) = $\bigcup_{\sigma \in K} \text{edges}(\sigma)$

Def: A geometric scx L is a subcomplex of a gscx K if $L \subseteq K$ [$L \subseteq K$].

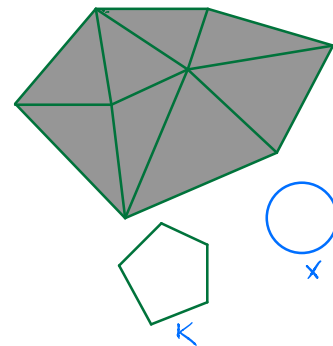
↳ $n \in \mathbb{N}$, n -skeleton of K : $K^{(n)} = \{\sigma \in K; \dim(\sigma) \leq n\}$



↳ $|K| = \bigcup_{\sigma \in K} \sigma \subset \mathbb{R}^d$ body of a scx K .

Def: A triangulation on $X \subset \mathbb{R}^d$ is a gscx K : $|K| = X$.

gscx L is a subdivision of a gscx K if it is obtained from K by subdividing scxs. ($|L| = |K|$).



③ Abstract simplicial complexes [ascx]

idea: forget the coordinates of vertices in a gscx, assign labels instead.

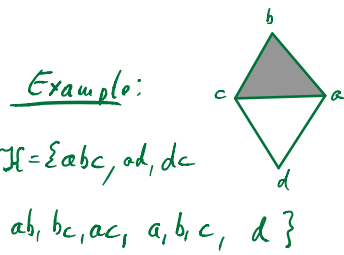
Def: let W be a finite set. An **ascx** \mathcal{K} on W is a family of subsets of W satisfying:

$$F \in \mathcal{K}, G \subset F \Rightarrow G \in \mathcal{K}.$$

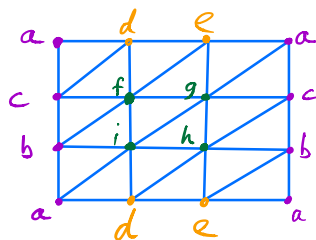
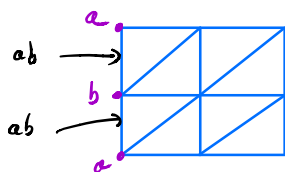
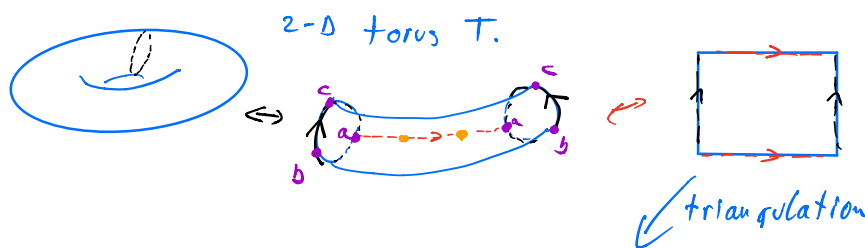
\hookrightarrow abstract sx [asx]: any non-empty element of \mathcal{K}

$\hookrightarrow F \subset G \in \mathcal{K}$:

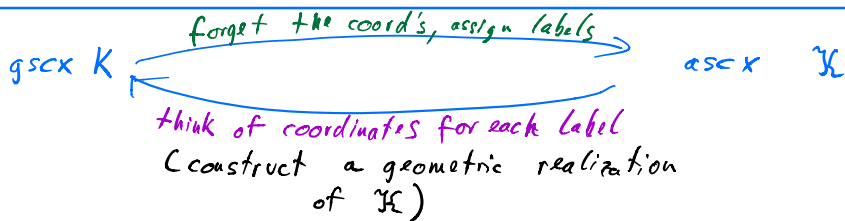
- F is a face of G
- G is a coface of F
- $\dim(F) = |F| - 1$.
- $\dim \mathcal{K} = \max_{H \in \mathcal{K}} \dim(H)$



Example:



acd, def,
 ...
 18 - triangles
 #₁ - edges
 #₂ - vertices



Thm: Every ascx \mathcal{X} of dimension d admits a geometric realization in \mathbb{R}^{2d+1} .

@ $d=1$, \mathcal{X} is a graph. There are graphs, which are not planar. K_5

Def: A topological invariant $i(x)$ is an object (#, vector, function, ...) assigned to a metric space so that: $X \cong Y \Rightarrow i(x) = i(y)$.

(Similarly: homotopy invariants: $X \simeq Y \Rightarrow j(x) = j(y)$).

Two homotopy invariants:

① # of components

② χ Euler characteristic of an ascx K .

$$\chi(K) = \sum_{i=0}^{\dim K} (-1)^i \cdot [\# \text{ of } i\text{-sxes of } K].$$

$$\hookrightarrow \chi(D^n) = 1, \text{ for } n \in \mathbb{N}.$$

$$\hookrightarrow \chi(\text{Torus}) = 0.$$

④ Simplicial maps

Def: Assume K, L are ascx's. A simplicial map $f: K \rightarrow L$ is an assignment

$f: K^{(0)} \rightarrow L^{(0)}$ satisfying

$$\sigma = \{v_0, v_1, \dots, v_m\} \in K \Rightarrow f(\sigma) = \{f(v_0), f(v_1), \dots, f(v_m)\} \in L \quad (*)$$

we could see repetition here

Ex:

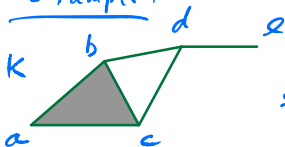


$$a \mapsto e$$

$$b \mapsto e$$

$$c \mapsto f$$

Example:



simplicial map

$$g: K \rightarrow K$$

$$\begin{array}{ll} a \mapsto a & a \mapsto a \\ d \mapsto d & b \mapsto c \\ e \mapsto b & c \mapsto c \end{array}$$

Def: Assume K, L are gscx's. Map $f: K \rightarrow L$ is *simplicial* if:

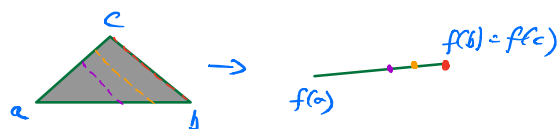
(a) the induced map on vertices is simplicial

$$(f(\text{vertex}) = \text{vertex} \quad \& \quad (\neq))$$

(b) f is linear on each sx $\{v_0, v_1, \dots, v_k\}$:

$$f\left(\sum_{i=1}^m \alpha_i v_i\right) = \sum_{i=1}^m \alpha_i f(v_i)$$

$$\forall \alpha_i \in [0,1], \sum_{i=1}^m \alpha_i = 1$$



Proposition: K, L gscx's.

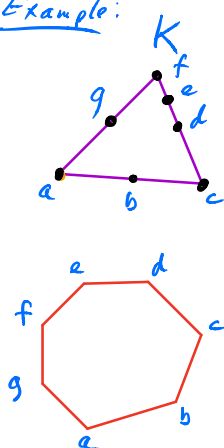
(1) Each simplicial map is continuous.

(2) for each continuous map $g: K \rightarrow L$ there exist $n \in \mathbb{N}$ and

a simplicial map $f: \tilde{K} \rightarrow \tilde{L}$, such that $f \approx g$.

n^{th} barycentric subdivisions of K & L .

Example:



continuous map



simplicial approximation

